

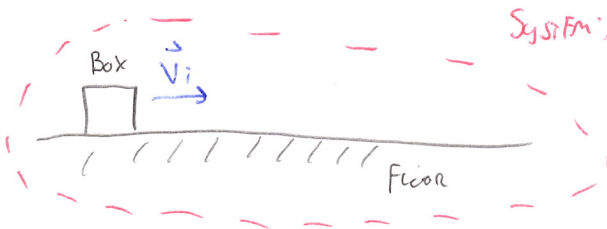
CQ 10.11



SYSTEM: BALL + EARTH + FLOOR

CQ 10.10

$$KE \rightarrow \Delta E^{th}$$

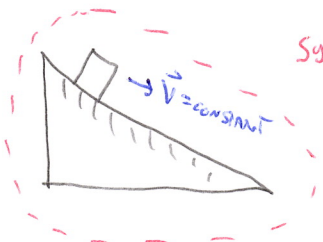


SYSTEM: Box + Floor

$$KE_{Box} \rightarrow \Delta E^{th}_{Box + Floor}$$

CQ 10.9

$$U \rightarrow \Delta E^{th}$$

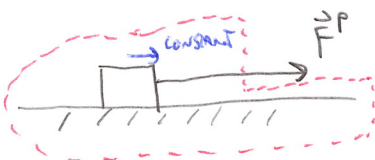


SYSTEM: Box + EARTH + INCLINE

$$U_{Box}^g \rightarrow \Delta E^{th}_{Box + INCLINE}$$

CQ 10.8

$$W \rightarrow \Delta E^{th}$$

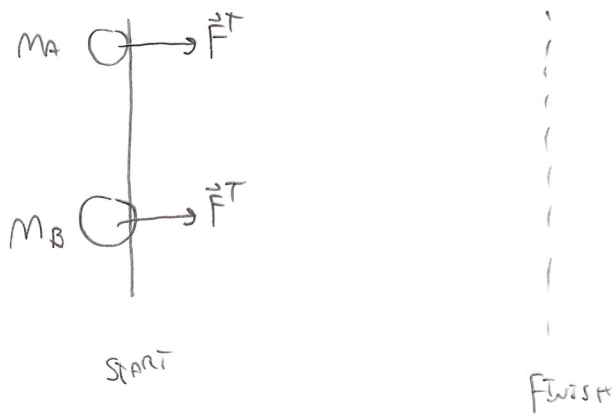


SYSTEM: Box + TABLE

$$W^p \rightarrow \Delta E^{th}_{Box + TABLE}$$

CQ 10.14

$$m_B = 3m_A$$



$$\Delta KE = W_{Ext}$$

$$\omega / \vec{v}_i = \vec{0}$$

$$\Delta KE \rightarrow KE_f$$

$$KE_f = W_{Ext}$$

$$\frac{1}{2} m v_f^2 = W^T$$

$$\frac{1}{2} m v_f^2 = \vec{F}^T \cdot \Delta \vec{r}$$

$$\left. \begin{array}{l} \omega / |\vec{F}^T| = \text{const.} \\ |\Delta \vec{r}| = \text{const} \\ \theta = \text{const} \end{array} \right\} W_A = W_B \rightarrow KE_{Af} = KE_{Bf}$$

$$\frac{1}{2} m_A v_{Af}^2 = \frac{1}{2} m_B v_{Bf}^2$$

$$m_A v_{Af}^2 = 3 m_A v_{Bf}^2$$

$$v_{Af}^2 = 3 v_{Bf}^2$$

$$v_{Af} = \sqrt{3} v_{Bf}$$